

## BIARGS Gynae Robotic bottom end Second Assistant

LEVEL 1.				
(Observed competencies ) Core logbook if opportunity available: S	TI/ST2 OR Nurse / All	ied Health professional =	Second assistant (Bott	om end)
LEVEL 2.				
( Able to undertake a skill under supervision . These will be main s	kills required for bed	side first assistant surgic	al skills) : ST/Practition	er
		OR Nurse / Allied Health		rst assistant
LEVEL 3.				
(Indirect supervision, competent to perform certain skills including	g console skills for m	edically or surgically appi	opriate cases = Robot	i <mark>c ATSM</mark>
LEVEL 4.			•	
( Unsupervised, independently competent to perform certain skills	s including console sk	ills for surgically approp	riate cases = Robotic A	TSM)
Trainees / Advanced surgical practitioner should have assisted wi	th a laparoscopic ca	ses before assisting with	robotic cases.	
	Date:	Name: (Trainee)	Trainer	
	Robot system			
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Orientation & Preparation		Compete	nce Level	
	Level 1	Level 2	Level 3	Level 4

Date

Signature Date

Signature

Date

Signature

Date

Signature

Orientation of robotic theatre								
Demonstrate effective team working	<del>                                     </del>							
Demonstrate effective communication skills within theatre team								
Demonstrate situational awareness				_				
Demonstrate importance of Human factor								†
Sterile preparation of robot								
Bedside assistant ( level 2)								
Reflective practice								
Knowledge				Compete	ance Leve	.1		
Milowieuge		Level 1		evel 2	tence Level Level 3		Level 4	
	Date	Signature		Signature	Date	Signature	Date	Signature
Completion of the basic online theoretical training package								
Understands mechanics of the Robotic assisted surgery								
knowledge of principles of laparoscopy and robotic surgery								
Situational awareness								
Communication skills								
General knowledge /Surgical competence	Competence Level							
	Level 1		Level 2		Level 3		Level 4	
	Date	Signature	Date	Signature	Date	Signature	Date	Signature
Knowledge of abdominal and pelvic anatomy								
Aware principles of managing a critically ill surgical patient								
Online modules								
- Consoles								
- Docking								
- Instrument insertion								
- Instrument removal								
- Undocking	<u> </u>							

Simulator training	Introduction							
Robotic Assistant competence	Competence Level							
	Level 1		Level 2		Level 3		Le	vel 4
	Date	Signature	Date	Signature	Date	Signature	Date	Signature
Knowledge of the operative room setup of the robotic system								
Aware of principles of the robotic system								
Be able to drape the Robot								
Be able to respond to system errors								
Able to drive the robot								
Knowledge of how to position patient for robotic surgery								
Undertake vaginal preparation for a robotic procedure								
Able to insert McCartney tube in vagina if required								
Able to insert uterine manipulator if required								
Be able to undertake vaginal preparation & insert a rectal probe if	required							
Understand and demonstrate use of different methods of maintaining pneumoperitoneum			um					
Demonstrate understanding port placement								
Understand different docking positions								
Able to retrieve specimen from vagina								
Demonstrate understanding of specimen handling and								
histology/cytology requests								
Demonstrate skills of communication with recovery and								
ward staff								

Name: Trainee:		
Name: Trainer :		
Institute:		
Level of training:		
Date:		